


 **HUMAN-COMPUTER INTERACTION** THIRD EDITION  DIX FINLAY ABOWD BEALE

chapter 15



task models

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What is Task Analysis?

Methods to analyse people's jobs:

- what people do
- what things they work with
- what they must know

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An Example

- in order to clean the house
 - get the vacuum cleaner out
 - fix the appropriate attachments
 - clean the rooms
 - when the dust bag gets full, empty it
 - put the vacuum cleaner and tools away
- must know about:
 - vacuum cleaners, their attachments, dust bags, cupboards, rooms etc.

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Approaches to task analysis

- Task decomposition
 - splitting task into (ordered) subtasks
- Knowledge based techniques
 - what the user knows about the task and how it is organised
- Entity/object based analysis
 - relationships between objects, actions and the people who perform them
- lots of different notations/techniques

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general method

- observe
- collect unstructured lists of words and actions
- organize using notation or diagrams

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Differences from other techniques

Systems analysis	vs.	Task analysis
system design		focus - the user
Cognitive models	vs.	Task analysis
internal mental state		focus - external actions
practiced 'unit' task		focus - whole job

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Task Decomposition

Aims:
 describe the actions people do
 structure them within task subtask hierarchy
 describe order of subtasks

Variants:
 Hierarchical Task Analysis (HTA)
 most common
 CTT (CNUCE, Pisa)
 uses LOTOS temporal operators

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Textual HTA description

Hierarchy description ...

0. in order to clean the house
 1. get the vacuum cleaner out
 2. get the appropriate attachment
 3. clean the rooms
 - 3.1. clean the hall
 - 3.2. clean the living rooms
 - 3.3. clean the bedrooms
 4. empty the dust bag
 5. put vacuum cleaner and attachments away

... and plans
 Plan 0: do 1 - 2 - 3 - 5 in that order. when the dust bag gets full do 4
 Plan 3: do any of 3.1, 3.2 or 3.3 in any order depending on which rooms need cleaning

N.B. only the plans denote order

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Generating the hierarchy

- 1 get list of tasks
- 2 group tasks into higher level tasks
- 3 decompose lowest level tasks further

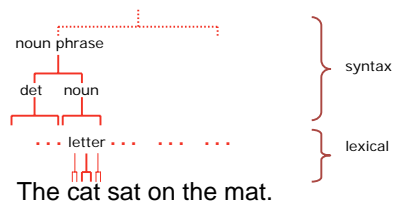
Stopping rules
 How do we know when to stop?
 Is "empty the dust bag" simple enough?
 Purpose: expand only relevant tasks
 Motor actions: lowest sensible level

Tasks as explanation

- imagine asking the user the question:
what are you doing now?
- for the same action the answer may be:
typing ctrl-B
making a word bold
emphasising a word
editing a document
writing a letter
preparing a legal case

HTA as grammar

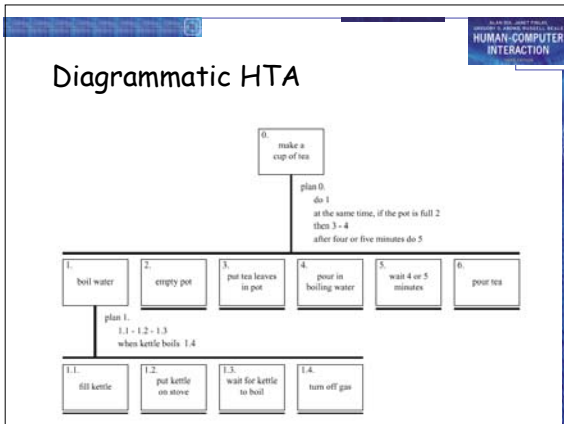
- can parse sentence into letters, nouns, noun phrase, etc.



parse scenario using HTA

- get out cleaner ————— 1.
- fix carpet head ————— 2.
- clean dinning room — 3.2. — 3.
- clean main bedroom — 3.3. — 3.
- empty dustbag ————— 4.
- clean sitting room — 3.2. — 4.
- put cleaner away ————— 5.

0. in order to clean the house
 1. get the vacuum cleaner out
 2. get the appropriate attachment
 3. clean the rooms
 - 3.1. clean the hall
 - 3.2. clean the living rooms
 - 3.3. clean the bedrooms
 4. empty the dust bag
 5. put vacuum cleaner and attachments away



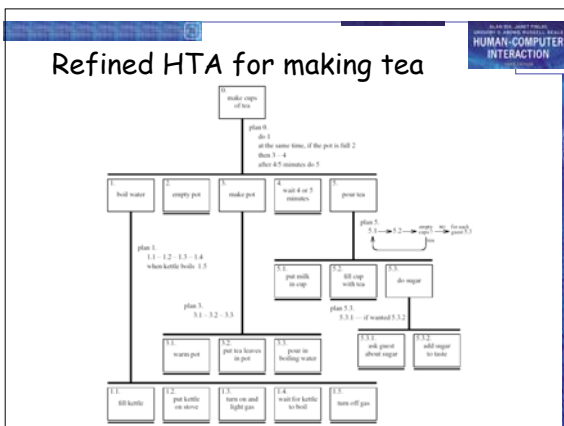
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Refining the description

Given initial HTA (textual or diagram)
How to check / improve it?

Some heuristics:

- paired actions e.g., where is 'turn on gas'
- restructure e.g., generate task 'make pot'
- balance e.g., is 'pour tea' simpler than making pot?
- generalise e.g., make one cup or more



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Types of plan

- fixed sequence - 1.1 then 1.2 then 1.3
- optional tasks - if the pot is full 2
- wait for events - when kettle boils 1.4
- cycles - do 5.1 5.2 while there are still empty cups
- time-sharing - do 1; at the same time ...
- discretionary - do any of 3.1, 3.2 or 3.3 in any order
- mixtures - most plans involve several of the above

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waiting ...

- is waiting part of a plan? ... or a task?
- generally
 - task - if 'busy' wait
 - you are actively waiting
 - plan - if end of delay is the event
 - e.g. "when alarm rings", "when reply arrives"
- in this example ...
 - perhaps a little redundant ...
 - TA not an exact science

see chapter 19 for more on delays!

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Knowledge Based Analyses

Focus on:

- Objects - used in task
- Actions - performed

+ Taxonomies - represent levels of abstraction

Knowledge-Based Example ...

```

motor controls
  steering steering wheel, indicators
  engine/speed
    direct ignition, accelerator, foot brake
    gearing clutch, gear stick
lights
  external headlights, hazard lights
  internal courtesy light
wash/wipe
  wipers front wipers, rear wipers
  washers front washers, rear washers
heating temperature control, air direction,
  fan, rear screen heater
parking hand brake, door lock
radio numerous!
  
```

Task Description Hierarchy

Three types of branch point in taxonomy:

- XOR – normal taxonomy
object in one and only one branch
- AND – object must be in both
multiple classifications
- OR – weakest case
can be in one, many or none

```

wash/wipe AND
  function XOR
    wipe front wipers, rear wipers
    wash front washers, rear washers
  position XOR
    front front wipers, front washers
    rear rear wipers, rear washers
  
```

Larger TDH example

```

Kitchen item AND
/_shape XOR
/ |__dished mixing bowl, casserole, saucepan,
/ | soup bowl, glass
/ |__flat plate, chopping board, frying pan
/_function OR
{__preparation mixing bowl, plate, chopping board
{__cooking frying pan, casserole, saucepan
{__dining XOR
|__for food plate, soup bowl, casserole
|__for drink glass
  
```

N.B. ' / | { ' used for branch types.

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More on TDH

Uniqueness rule:
– can the diagram distinguish all objects?

e.g., plate is:
kitchen item/shape(flat)/function{preparation,dining(for food)}/
nothing else fits this description

Actions have taxonomy too:
kitchen job OR
|___ preparation *beating, mixing*
|___ cooking *frying, boiling, baking*
|___ dining *pouring, eating, drinking*

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Abstraction and cuts

After producing detailed taxonomy
‘cut’ to yield abstract view

That is, ignore lower level nodes
e.g. cutting above shape and below dining, plate becomes:
kitchen item/function{preparation,dining}/

This is a term in Knowledge Representation Grammar (KRG)

These can be more complex:
e.g. ‘beating in a mixing bowl’ becomes:
kitchen job(preparation) using a
kitchen item/function{preparation}/

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Entity-Relationship Techniques

Focus on objects, actions and their relationships

Similar to OO analysis, but ...

- includes non-computer entities
- emphasises domain understanding not implementation

Running example
‘Vera’s Veggies’ – a market gardening firm
owner/manager: Vera Bradshaw
employees: Sam Gummage and Tony Peagreen
various tools including a tractor ‘Fergie’
two fields and a glasshouse
new computer controlled irrigation system

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Actions (ctd)

implicit agents – read behind the words
 `the field was ploughed' – *by whom?*

indirect agency – the real agent?
 `Vera programmed the *controller* to irrigate the field'

messages – a special sort of action
 `Vera *told* Sam to ... '

rôles – an agent acts in several rôles
 Vera as *worker* or as *manager*

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example - objects and actions

<p>Object Sam human actor Actions: S1: drive tractor S2: dig the carrots</p>	<p>Object glasshouse simple Attribute: humidity: 0-100%</p>
<p>Object Vera human actor – the proprietor Actions: as worker V1: plant marrow seed V2: program irrigation controller Actions: as manager V3: tell Sam to dig the carrots</p>	<p>Object Irrigation Controller non-human actor Actions: IC1: turn on Pump1 IC2: turn on Pump2 IC3: turn on Pump3</p>
<p>Object the men composite Comprises: Sam, Tony</p>	<p>Object Marrow simple Actions: M1: germinate M2: grow</p>

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Events

... when something happens

- performance of action
 'Sam dug the carrots'
- spontaneous events
 'the marrow seed germinated'
 'the humidity drops below 25%'
- timed events
 'at midnight the controller turns on'

Relationships

- object-object
 - social - Sam is subordinate to Vera
 - spatial - pump 3 is in the glasshouse
- action-object
 - agent (listed with object)
 - patient and instrument
- actions and events
 - temporal and causal
 - 'Sam digs the carrots because Vera told him'
- temporal relations
 - use HTA or dialogue notations.
 - show task sequence (normal HTA)
 - show object lifecycle

example - events and relations

Events:

- Ev1: humidity drops below 25%
- Ev2: midnight

Relations: object-object

- location (Pump3, glasshouse)
- location (Pump1, Parker's Patch)

Relations: action-object

- patient (V3, Sam)
 - Vera tells Sam to dig
- patient (S2, the carrots)
 - Sam digs the carrots ...
- instrument (S2, spade)
 - ... with the spade

Relations: action-event

- before (V1, M1)
 - the marrow must be sown
 - before it can germinate
- triggers (Ev1, IC3)
 - when humidity drops below 25%, the controller turns on pump 3
- causes (V2, IC1)
 - the controller turns on the pump because Vera programmed it

Sources of Information

Documentation

- N.B. manuals say what is *supposed* to happen but, good for key words and prompting interviews

Observation

- formal/informal, laboratory/field (see Chapter 9)

Interviews

- the expert: manager or worker? (ask both!)

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Early analysis

Extraction from transcripts

- list nouns (objects) and verbs (actions)
- beware technical language and context:
`the rain poured' vs. `I poured the tea'

Sorting and classifying

- grouping or arranging words on cards
- ranking objects/actions for task relevance (see ch. 9)
- use commercial outliner

Iterative process:
data sources ↔ analysis
... but costly, so use cheap sources where available

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Uses - manuals & documentation

Conceptual Manual

- from knowledge or entity-relations based analysis
- good for open ended tasks

Procedural 'How to do it' Manual

- from HTA description
- good for novices
- assumes all tasks known

<p style="text-align: center;">To make cups of tea</p> <p>boil water — see page 2 empty pot make pot — see page 3 wait 4 or 5 minutes pour tea — see page 4</p> <p style="text-align: center;">— page 1 —</p>	<p style="text-align: center;">Make pot of tea <i>(since water has boiled)</i></p> <p>warm pot put tea leaves in pot pour in boiling water</p> <p style="text-align: center;">— page 3 —</p>
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Uses - requirements & design

Requirements capture and systems design

- lifts focus from system to use
- suggests candidates for automation
- uncovers user's conceptual model

Detailed interface design

- taxonomies suggest menu layout
- object/action lists suggest interface objects
- task frequency guides default choices
- existing task sequences guide dialogue design

NOTE. task analysis is never complete

- rigid task based design ⇒ inflexible system
